Paint Mate 200*i*A & Paint Mate 200*i*A/5L

Basic Description

FANUC Robotics' Paint Mate robot is a compact, electric servo-driven paint robot with best-in-class performance designed for operation in a hazardous environment. Based on the highly-acclaimed LR Mate® series, this robot's envelopes, speed, and dexterity are a perfect fit for coatings and hazardous duty applications. The Paint Mate can be used for small parts painting or a material saving alternative to multiple fixed guns.

Paint Mate, the Solution for:

- Painting
- Coating
- Assembly and Handling in Hazardous Environments
- Material removal where hazardous cooling chemicals are present
- Dispensing

Features

- iPendant[™], a color, Internetready teach pendant for even easier programming and custom cell user interface design.
- Optional one or four pneumatic three-way solenoid valves located in the purge cavity for gun triggering capability.
- Floor, invert, angle and wall mounting permits versatility for robot location and allows for minimal spray booth size.
- Absolute serial encoders eliminate the need for calibration at power-up.
- Standard FANUC Robotics purge control.



- Approved for use in hazardous locations; see specifications for details.
- FM: Flex field and rigid conduit ATEX: ROX
- Tabletop size, slim wrist, and small footprint permit operation in tight work spaces
- Extremely fast acceleration and deceleration motion results in faster cycle times.
- Control Reliable Safety Circuit (RIA1506.1999 compliant)

Reliability and Maintenance Advantages

- The latest generation of a proven design
- Sealed bearings and brushless AC motors
- Purged and pressurized cavities
- Designed for painting environment

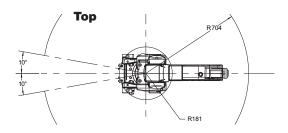
Software

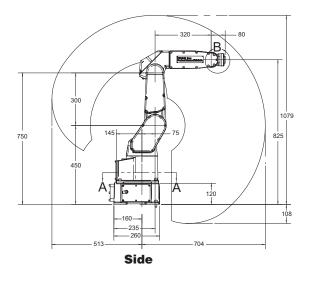
Two standard software applications are available:

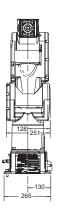
- HandlingToolTM allows for the setup, programming, and operation for basic and custom applications. Built-in macro functions including paint application plug-in routines and menu-driven programming tools allow users to create, test, and run robot application programs with minimal training and program assistance.
- PaintTool[™] software with optional configurations for stand alone or multi robot systems with built-in paint function controls:
 - Analog parameter control
 - Color change control
 - "Cancel/Continue" feature
 - Integral 2K variable ratio
 Pump Control
 - ACCUFLOW[™] closed-loop fluid control.
 - Line tracking
 - Collision detection
 - Internet connectivity
 - KAREL® programming language

Process control hardware must be added separately.

Dimensions Paint Mate 200*i*A

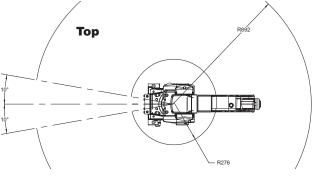


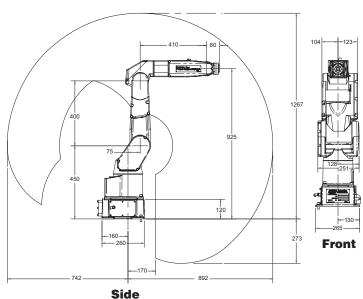




Front

Paint Mate 200iA/5L

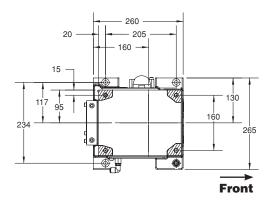




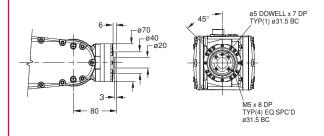
Paint Mate Isometric



Footprint (All models)



Wrist (All models)



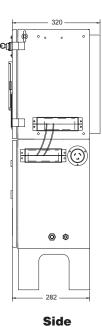
Paint Mate Series Robot Specifications

R-30iA Mate Controller Dimensions

Top

Items		Paint Mate 200iA	Paint Mate 200iA/5L
Axes		6	6
Payload - wrist (kg)		5	5
Reach (mm)		704	892
Repeatability (mm)		±0.02	±0.03
Interference Radius (mm)		181	181
Motion range	J1	340	340
(degrees)	J2	200	230
	J3	388	373
	J4	380	380
	J5	240	240
	J6	720	720
Motion speed	J1	350	270
(degrees/s)	J2	350	270
	J3	400	270
	J4	450	450
	J5	450	450
	J6	720	720
Wrist moments N-m	J4	11.9 (1.21)	11.9 (1.21)
(kgf-m)	J5	11.9 (1.21)	11.9 (1.21)
	J6	6.7 (0.68)	6.7 (0.68)
Wrist load inertia	J4	0.3	0.3
(kg-m²)	J5	0.3	0.3
	J6	0.1	0.1
Mechanical brakes		All axes	All axes
Mechanical weight (kg)		35	37
Mounting method ⁽¹⁾		Floor, ceiling, angle and wall	
Installation environmen	t		
Temperature (°C)		0 to 45	
Humidity		Normally: 75% or less Short term (within a month): 95% or less No condensation	
Vibration m/s ² (G)		0.5 or less	
Ratings		FMuc Class I, II, III, Div I, Group C, D, E, F, G T4 45°C Ambient ATEX (€ II 2 G c Ex ib px IIB T4 Ta=0°C to +45°C ATEX (€ II 2 D c Ex pD 21 T 135°C Ta=0° to +45°C Note: iPendant™ for non-hazardous areas only	

Front



Note: (1) J1 and J2 axes motion range will be limited for angle and wall mount installations.

R-30*i*A™ Mate Controller Specifications

Items			
External Dimensions (mm)	- 470(W) x 320(D) x 950(H)		
Weight	- 56 kg		
Operating Environment	- Ambient temperature: 0 - 45 ° C (R-30 <i>i</i> A Mate) Humidity: 75% RH or less; Short term (within a month): 95% or less Vibration: 0.5G or less		
Power Supply	- 200-230VAC Single Phase; +10%, -15%, 50/60 Hz ± 1Hz		
Power Consumption	- 0.5 KW (average), 1.2 KVA (maximum)		
CPU	- Multi-processor architecture (separate motion and communication) with real-time clock/calendar		
Controlled Axes	- 24 (up to 5 motion groups for R-30iA Mate)		
Serial/ host communications	- One 100 Base-TX/10 Base-T Ethernet port with RJ-45 connector - One RS-232-C / RS-485 port		
Teach Pendant	 Color graphic iPendant™ with available touch screen option (Not in hazardous area) 		
<i>i</i> RVision [®]	- Built-in camera interface for 2-D vision applications Optional: multiplexer for multiple 2-D cameras and 3-D vision		
Built-in I/O	- Up to 28 digital inputs / 24 digital outputs 24VDC (external 24VDC power supply is required for digital outputs)		
Safety Features	- Dual Check Safety (DCS) circuit		
Memory Card	- PCMCIA type 2 interface: ATA flash disk (SanDisk compatible)		
R-30/A Mate Controller Options:			
I/O sub-systems	Model A I/O (remote mounted modular rack- 5 or 10 slots) Model B I/O (distributed DIN rail mounted) FANUC I/O link		
Remote I/O sub-systems	DeviceNet (single channel slave) Profibus DP slave/master CC-Link (slave) Ethernet I/O (EGD and EIP Adapter/Scanner)		
Integrated PMC	- Ladder logic control for peripheral devices - Including ladder monitor with hot edit on iPendant		

Isometric



Note: Dimensions are shown in millimeters.

Detailed CAD data is available upon request.



Paint Mate - Maximum performance at minimal cost. Affordable robotic automation for small parts coating.



Class 1 Division 1 hazardous approval ratings enables the Paint Mate robot to be used for handling applications in explosive and extreme environments

